

Invariants of the spherical sector in conformal mechanics

Tigran Hakobyan

Yerevan State University & Yerevan Physics Institute, Armenia

The talk is based on the results obtained in collaboration with
S. Krivonos, O. Lechtenfeld, A. Nersessian, A. Saghatelyan, V. Yeghikyan

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The goal of the talk

The main goal of this talk is the investigation of the spherical (angular) part of the conformal mechanics. Considered as a separate Hamiltonian, it describes a mechanical system on the sphere, which we call briefly a "spherical mechanics".

In particular, we will

- Study the relation of the spherical part with other constants of motion of the general conformal mechanical system.
- Construct the constants of motion for spherical mechanics using the constants of motion in the underlying conformal mechanics.
- Construct the complete set of integrals in $2D$ spherical mechanics associated to the four-particle rational Calogero model.

The talk is based on the publications: (1) Hakobyan, Lechtenfeld, Nersessian, Saghatelian, *Invariants of the spherical sector in conformal mechanics*, arXiv:1008.2912; (2) Hakobyan, Krivonos, Lechtenfeld, Nersessian, *Hidden symmetries of integrable conformal mechanical systems*, Phys. Lett. A **374**, 801 (2010); (3) Hakobyan, Nersessian, Yeghikyan, *Cuboctahedric Higgs oscillator from the Calogero model*, J. Phys. A **42**, 205206 (2009).

Motivation

- The relation of the spherical part of the Hamiltonian with other constants of motion has not been investigated properly so far.
- In particular, for the rational Calogero model, it is not a Liouville integral, but related to the additional integrals responsible for the superintegrability. It would be interesting to obtain the exact links among them.
- The study of the spherical mechanics has its own interest. It describes a particle motion on the sphere interacting with some potential fields, which can be considered as some multi-center high dimensional generalization of the spherical Higgs oscillator.
- The spherical mechanics of the Calogero model was used for the explanation of the non-equivalence of different quantizations of the Calogero model [Feher, Tsutsui, Fulop, 2005], as well as for the construction its superconformal generalizations [Bellucci, Krivonos, Sutulin, 2008].

Conformal Mechanics

The Hamiltonian of the conformal mechanics is [De Alfaro, Fubini, Furlan, 1974]

$$H = \frac{\vec{p}^2}{2} + V(\vec{r}), \quad (\vec{r} \cdot \vec{\nabla}) V(\vec{r}) = -2V(\vec{r}).$$

Together with the dilatation and special conformal transformation

$$D = \vec{p} \cdot \vec{r}, \quad K = \frac{\vec{r}^2}{2},$$

it forms the conformal algebra $so(2,1)$

$$\{H, D\} = 2H, \quad \{K, D\} = -2K, \quad \{H, K\} = D.$$

Invariant representation:

$$J_{1,3} = H \pm K, \quad J_2 = D : \quad \{J_a, J_b\} = -2\varepsilon_{abc} J^c,$$

The indexes upper by $\gamma_{ab} = \text{diag}(1, -1, -1)$.

The spherical part \mathcal{I} : spherical mechanics

The Casimir of $so(2, 1)$ is a constant of motion quadratic on momenta:

$$\mathcal{I} = 4KH - D^2 = \sum_a J_a J^a, \quad \{H, \mathcal{I}\} = 0.$$

In any spherical coordinates with the radial coordinates $r = \sqrt{2K}$ and $p_r = \frac{D}{\sqrt{2K}}$, we have:

$$\{p_r, r\} = 1, \quad D = rp_r, \quad K = \frac{r^2}{2}, \quad H = \frac{p_r^2}{2} + \frac{\mathcal{I}}{2r^2},$$

where the Casimir element $\mathcal{I} = \mathcal{I}(u)$ depends on the angular coordinates $u = \{p_{\phi_\alpha}, \phi_\alpha\}$ only.

The spherical mechanics given by the Hamiltonian $\mathcal{I}(u)$ describes a particle on $(N - 1)$ -dimensional sphere moving in the presence of the external potential.

Notation: Denote by \hat{F} the associated Hamiltonian vector field: $\hat{F}G := \{F, G\}$. In particular, $\hat{\mathcal{I}} = 4H\hat{K} + 4K\hat{H} - 2D\hat{D}$.

Integrals of conformal mechanics

Suppose, we have an integral of motion in the conformal mechanics. Without loss of generality, consider the integrals with a certain conformal spin:

$$\hat{H}I_s = \{H, I_s\} = 0, \quad \hat{D}I_s = \{D, I_s\} = -2s I_s.$$

The conservation condition is equivalent to the equation

$$(\hat{\mathcal{I}} - \hat{M}) I_s(p_r, r, u) = 0, \quad \hat{M} = 2\hat{S}_- - 2\mathcal{I}\hat{S}_+, \quad (1)$$

where the 1D vector fields

$$\hat{S}_+ = \frac{1}{r} \frac{\partial}{\partial p_r}, \quad \hat{S}_- = -p_r r^2 \frac{\partial}{\partial r}, \quad \hat{S}_z = -\frac{1}{2} \left(r \frac{\partial}{\partial r} + p_r \frac{\partial}{\partial p_r} \right).$$

form $so(3)$ algebra, Decompose I_s in terms of spherical and radial functions

$$I_s(p_r, r, u) = \sum_{m=-s}^s f_{s,m}(u) R_{s,m}(p_r, r), \quad R_{s,m}(p_r, r) = \sqrt{\binom{2s}{s+m}} \frac{p_r^{s-m}}{r^{s+m}}.$$

The radial functions $R_{s,m}$ form standard spin s -representation of the $so(3)$ algebra \hat{S}_\pm, \hat{S}_z .

Equations of motion for the coefficients $f_{s,m}$ in spherical mechanics

From (1), the equations of motion of the $2s+1$ angular coefficients $f_{s,m}(u)$ in the spherical mechanics \mathcal{I} is given by linear equations

$$\begin{aligned}\frac{df_{s,m}}{dt_{\mathcal{I}}} &= \hat{\mathcal{I}}f_{s,m} = \sum_{m'=-s}^s M_{mm'} f_{s,m'} \\ &= 2\sqrt{(s-m)(s+m+1)}f_{s,m+1} - 2\mathcal{I}\sqrt{(s-m+1)(s+m)}f_{s,m-1}.\end{aligned}\quad (2)$$

The related $(2s+1)$ th-order linear homogeneous differential equation is

$$\text{Det}(\hat{\mathcal{I}} - M)f_{s,m} = 0. \quad (3)$$

As a consequence, from the set of derivative integrals $I_s^{(k)} := \hat{\mathcal{I}}^k I_s$ obtained from I_s ,

$$I_s \xrightarrow{\hat{\mathcal{I}}} I_s^{(1)} \xrightarrow{\hat{\mathcal{I}}} I_s^{(2)} \xrightarrow{\hat{\mathcal{I}}} \dots \xrightarrow{\hat{\mathcal{I}}} I_s^{(k)} \xrightarrow{\hat{\mathcal{I}}} \dots$$

the first $(2s+1)$ integrals *at most* may be functionally independent.

Properties of the spherical coefficients

- The map $l_s \rightarrow f_{s,-s}$ (the contraction $r \rightarrow \infty$) is a Poisson algebra homomorphism ($l_s = f_{s,-s} p_r^{2s} + \sqrt{2s} f_{s,-s+1} \frac{p_r^{2s-1}}{r} + \dots$):

$$l_{s_1} l_{s_2} \rightarrow f_{s_1, -s_1} f_{s_2, -s_2}, \quad \{l_{s_1}, l_{s_2}\} \rightarrow \{f_{s_1, -s_1}, f_{s_2, -s_2}\}.$$

- The integral l_s is completely determined by its leading coefficient on p_r , the others are defined recursively using the equation of motion (2):

$$f_{s,-s+1} = \frac{1}{2\sqrt{2}} \hat{\mathcal{I}} f_{s,-s}, \quad f_{s,-s+2} = \frac{1}{\sqrt{s(2s-1)}} \left(\frac{1}{8} \hat{\mathcal{I}}^2 + s\mathcal{I} \right) f_{s,-s}, \quad \dots$$

- From two integral l_{s_1} and l_{s_2} , the "new" integrals can be constructed using the Clebsch-Gordan coefficients:

$$l'_S = \sum_m f'_{S,m} R_{S,m}, \quad f'_{S,m} = \sum_{m_1+m_2=m} C_{s_1 m_1, s_2 m_2}^{S m} f_{s_1, m_1} f_{s_2, m_2},$$

where $|s_1 - s_2| \leq S \leq s_1 + s_2$. In particular, $l'_{s_1+s_2} = l_{s_1} l_{s_2}$.

The solutions to the equations of motion for $f_{s,m}$

The formal solution is provided by the diagonalization of the matrix M ,

$$\hat{M} = 4\sqrt{-\mathcal{I}} \hat{U} \hat{S}_z \hat{U}^{-1}, \quad \hat{U} = (-\mathcal{I})^{\frac{1}{2}} \hat{S}_z e^{-\frac{i\pi}{2} \hat{S}_y}$$

The eigenfunctions of the operator \hat{M} are

$$\tilde{R}_{s,m} = \sum_{m'} U_{m'm} R_{s,m'}, \quad U_{m'm} = d_{m'm}^s(\pi/2)(-\mathcal{I})^{\frac{m'}{2}}, \quad \hat{M} \tilde{R}_{s,m} = m \tilde{R}_{s,m},$$

where $d_{m'm}^s(\beta)$ is the Wigner's small d -matrix, which describes the rotation around the y axis in the spin- s representation.

In terms of the rotated radial functions, the expression of the integral becomes

$$I_s(p_r, r, u) = \sum_{m=-s}^s \tilde{f}_{s,m}(u) \tilde{R}_{s,m}(p_r, r, \mathcal{I}(u)),$$
$$\tilde{f}_{s,m} = \sum_{m'} U_{mm'}^{-1} f_{s,m'} = \sum_{m'} (-\mathcal{I})^{-\frac{m'}{2}} d_{m'm}^s(\pi/2) f_{s,m'}.$$

The solutions to the equations of motion and integrals of \mathcal{I}

The rotated coefficients are (in general, complex) eigenfunctions of \mathcal{I} and oscillate in time with the frequency $\omega_m = 4m\sqrt{\mathcal{I}}$:

$$\hat{\mathcal{I}}\tilde{f}_{s,m}(u) = i\omega_m\tilde{f}_{s,m}(u), \quad \tilde{f}_{s,m}(t) = e^{i\omega_m(t-t_0)}\tilde{f}_{s,m}(t_0),$$

Using the eigenvalues of M , we obtain

$$\text{Det}(\hat{\mathcal{I}} - M) = \prod_{m=-s}^s (\hat{\mathcal{I}} - 4m\sqrt{-\mathcal{I}}) =: \begin{cases} \hat{\mathcal{I}}\hat{\Delta}_s & \text{for } s \in \mathbb{Z}, \\ \hat{\Delta}_s & \text{for } s \in \mathbb{Z} + \frac{1}{2}, \end{cases}$$

$$\hat{\Delta}_s = \prod_{0 < m \leq s} (\hat{\mathcal{I}}^2 + 16m^2\mathcal{I}).$$

So, the exact form of the equations (3) is

$$\hat{\Delta}_s f_{s,m} = 0 \quad \text{for } s = \frac{1}{2}, \frac{3}{2}, \dots, \quad \text{and} \quad \hat{\mathcal{I}}\hat{\Delta}_s f_{s,m} = 0 \quad \text{for } s = 1, 2, \dots$$

This means that for integer spins, $\hat{\Delta}_s f_{s,m}$ is an integral of motion (if nonzero) of the spherical mechanics \mathcal{I} .

Integrals of motion of the spherical mechanics linear in $f_{s,m}$

An integral I_s of the conformal mechanics H can be used to construct integrals of motion of the related spherical mechanics \mathcal{I} . They have the simplest form while expressed in terms of the oscillated complex functions $\tilde{f}_{s,m}(u)$. We consider linear and bilinear expressions mainly.

Integral of \mathcal{I} linear in $f_{s,m}$: integer spins only

For integer s , the $m = 0$ eigenfunction is an integral of \mathcal{I} . Using the explicit expression for $d_{mm'}^s(\pi/2)$, the modified integral (without the fractional powers of \mathcal{I}) is calculated

$$\mathcal{J}_s(u) = \mathcal{I}(u)^{\frac{s}{2}} \tilde{f}_{s,0}(u) = \sum_{\ell=0}^s \frac{(2\ell-1)!!(2s-2\ell-1)!!}{\sqrt{(2s)!}} \mathcal{I}(u)^\ell f_{s,2\ell-s}(u).$$

Two constructed integrals are similar. The inverse transformation $f_{sm} = \sum_{m'} U_{mm'} \tilde{f}_{sm'}$ gets

$$\hat{\Delta}_s f_{s,m} = U_{m0} \hat{\Delta}_s \tilde{f}_{s,0} = \delta_{s-m,2\mathbb{Z}} c_{sm} \mathcal{I}^{\frac{s+m}{2}} \mathcal{J}_s,$$

c_{sm} is a numerical coefficient.

Integrals bilinear in $f_{s,m}$

Other constants of motion can be built also by bilinear combinations of $f_{s,m}$.

The bilinear integrals, $0 < m \leq s$

The following observables are well-defined (real, without fractional powers of \mathcal{I}) constants of motion of \mathcal{I} :

$$\begin{aligned}\mathcal{J}_s^m &= (-\mathcal{I})^s \tilde{f}_{s,m} \tilde{f}_{s,-m} \\ &= \sum_{m',m''} \delta_{m''-m', 2\mathbb{Z}} (-1)^{2s+\frac{m''-m'}{2}} d_{m''m}^s(\pi/2) d_{m'm}^s(\pi/2) \mathcal{I}^{s-\frac{m'+m''}{2}} f_{s,m'} f_{s,m''}\end{aligned}$$

One can choose the total spin "quantum" number S instead of m to represent this set of integrals:

$$\mathcal{F}_s^S(u) = \sum_m C_{sm,s-m}^{S,0} \mathcal{J}_m^s(u).$$

Unwanted fractional powers of \mathcal{I} cancel in the expression.

Other integrals of \mathcal{I}

- The construction straightforwardly generalizes also to multilinear forms composed from the angular functions:

$$\mathcal{J}_{s_1 \dots s_k}^{m_1 \dots m_k}(u) = \mathcal{I}(u)^{\frac{1}{2} \sum_{\ell=1}^k s_{\ell}} \prod_{\ell=1}^k \tilde{f}_{s_{\ell}, m_{\ell}}(u) \quad \sum_{\ell=1}^k m_{\ell} = 0,$$

- The factors can also be taken into account like $\tilde{f}_{s_1, m}(u) / \tilde{f}_{s_2, m}(u)$.

A single integral I_s of the conformal mechanics H gives rise to a number of integrals of the spherical mechanics \mathcal{I} .

- The derived integrals are not independent, in general.
- If two integrals of the conformal mechanics are in involution, then the integrals of the spherical mechanics retrieved from them are not in involution. So, if H integrable with the Liouville integral set $\{I_s\}$, the related integrals of \mathcal{I} do not define the set of Liouville integrals.

Calogero model

A particular case of the conformal mechanics is the N -particle rational Calogero model [Calogero, 1969,1971]

$$H = \frac{1}{2} \sum_{i=1}^N p_i^2 + \sum_{i < j} \frac{g^2}{(x_i - x_j)^2}$$

- Is integrable with N Liouville constants of motion given in terms of a Lax matrix [Moser, 1975]

$$I_s = \text{Tr } L^{2s}, \quad s = \frac{1}{2}, 1, \dots, \frac{N}{2}, \quad L_{jk} = \delta_{jk} p_k + (1 - \delta_{jk}) \frac{ig}{x_j - x_k},$$

$$I_{\frac{1}{2}} = \sum_i p_i, \quad I_1 = H$$

- Maximally superintegrable: has additional constants of motion ($N - 1$ of them are independent) [Wojciechowski, 1973]

$$F_{s_1 s_2} = 2s_1 I_{s_1} \hat{K} I_{s_2} - 2s_2 I_{s_2} \hat{K} I_{s_1}.$$

The action of $\hat{\mathcal{I}}$ on the Liouville integrals produces the additional integrals:

$$I_s^{(1)} = \hat{\mathcal{I}} I_s = 2F_{1s}.$$

The spherical mechanics \mathcal{I} as an extended Higgs oscillator.

The angular part \mathcal{I} describes a particle motion on the sphere.

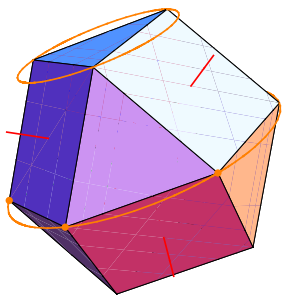
$$H = \frac{\vec{p}^2}{2} + \sum_{\vec{\alpha} \in \Delta_+} \frac{g^2}{(\vec{\alpha} \cdot \vec{x})^2} = \frac{p_r^2}{2} + \frac{\mathcal{I}(p_{\varphi_a}, \varphi_a)}{2r^2},$$

$$\mathcal{I}(p_{\varphi_a}, \varphi_a) = K_{\text{sph}}(p_{\varphi_a}, \varphi_a) + \sum_{\alpha=1}^{N(N-1)/2} \frac{2g^2}{\cos^2 \theta_\alpha}, \quad \{p_{\varphi_a}, \varphi_b\} = \delta_{ab}$$

- $\Delta_+ = \{\epsilon_i - \epsilon_j, i > j\}$ is the set of positive roots of A_N [Olshanetsky, Perelomov],
- $\cos \theta_\alpha = \vec{\alpha} \cdot \vec{x}$, where $\theta_\alpha = \theta_\alpha(\varphi_a)$,
- $\frac{1}{2}\omega^2 r_0^2 \tan^2 \theta$ is the potential of the Higgs oscillator on the sphere [Higgs, 1979].
- The center of mass of H can be reduced applying the orthogonal Jacobi transformations [Ioffe, Neelov, 2002].

The spherical part can be regarded as an integrable $\frac{1}{2}N(N-1)$ center high-dimensional extension of the Higgs oscillator with the frequency $\omega = 2g$.

The spherical mechanics of the four particle Calogero model with reduced center of mass



- The roots of A_3 Lie algebra are associated with the vertexes of cuboctahedron.
- The root system Δ has octahedral symmetry $O_h \equiv S_4 \otimes Z_2$ of order 48.

Three particle Calogero system: the algebra of integrals of motion

The spherical mechanics of $N = 3$ system with the reduced center-of-mass is $1D$ three-center Higgs oscillator [Jacobi]:

$$H = \frac{p_r^2}{2} + \frac{\mathcal{I}}{2r^2} \quad \mathcal{I} = p_\varphi^2 + \frac{9g^2}{\cos^2 3\varphi},$$

The $2D$ conformal mechanics H has two $s = \frac{3}{2}$ integrals

$$I_{\frac{3}{2}} = \left(p_r^2 - \frac{6\mathcal{I}}{r^2} \right) p_r \sin 3\varphi + \left(3p_r^2 - \frac{2\mathcal{I}}{r^2} \right) \frac{p_\varphi \cos 3\varphi}{r},$$
$$I_{\frac{3}{2}}^{(1)} = \hat{\mathcal{I}} I_{\frac{3}{2}} = \left(p_r^2 - \frac{6\mathcal{I}}{r^2} \right) 6p_r p_\varphi \cos 3\varphi - \left(3p_r^2 - \frac{2\mathcal{I}}{r^2} \right) \frac{12\mathcal{I} \sin 3\varphi}{r}.$$

The nontrivial brackets (including \mathcal{I}) are:

$$\{\mathcal{I}, I_{\frac{3}{2}}\} = I_{\frac{3}{2}}^{(1)}, \quad \{\mathcal{I}, I_{\frac{3}{2}}^{(1)}\} = -18\mathcal{I} I_{\frac{3}{2}}, \quad \{I_{\frac{3}{2}}^{(1)}, I_{\frac{3}{2}}\} = 18(8H^3 - I_{\frac{3}{2}}^2).$$

Of course, only 3 integrals are independent:

$$\left(I_{\frac{3}{2}}^{(1)} \right)^2 + 36\mathcal{I} I_{\frac{3}{2}}^2 = 8H^3(\mathcal{I} - 9g^2).$$

4 particle spherical mechanics: the Hamiltonian \mathcal{I}

The transformation (Jacobi transformation + reflection)

$$\begin{aligned}y_0 &= \frac{1}{2}(x_1+x_2+x_3+x_4), & y_1 &= \frac{1}{2}(x_1+x_2-x_3-x_4), \\y_2 &= \frac{1}{2}(x_1-x_2+x_3-x_4), & y_3 &= \frac{1}{2}(x_1-x_2-x_3+x_4)\end{aligned}$$

decouples the center-of-mass coordinate y_0 and momentum of $N = 4$ Calogero model. After reducing them and passing to the spherical coordinates, the spherical Hamiltonian takes the form

$$\mathcal{I}(p_\theta, p_\varphi, \theta, \varphi) = p_\theta^2 + \frac{p_\varphi^2}{\sin^2 \theta} + \frac{2g^2}{\sin^2 \theta} \times \sum_{\pm} \left[\frac{1}{(\cos \varphi \pm \sin \varphi)^2} + \frac{1}{(\cot \theta \pm \sin \varphi)^2} + \frac{1}{(\cot \theta \pm \cos \varphi)^2} \right],$$

with the spherical symplectic structure $\omega_0 = dp_\theta \wedge d\theta + dp_\varphi \wedge d\varphi$.

It has 3 independent integrals (is max. superintegrable). As for general conformal mechanics, try to extract them from the integrals of underlying system $H = \frac{1}{2}(p_r^2 + \mathcal{I}/r^2)$.

4 particle Calogero: the algebra of integrals

The conformal Hamiltonian has two Liouville constants of motion $I_s = \text{Tr} L^{2s}$ of conformal spin $s = \frac{3}{2}, 2$. Their leading-term coefficients $f_s := f_{s,-s}$ in the decomposition $I_s = \sum_m f_{s,m} R_{s,m}$ can be calculated easily:

$$f_{\frac{3}{2}}(\theta, \varphi) = \frac{3}{2} \cos \theta \sin^2 \theta \sin 2\varphi, \quad f_2(\theta, \varphi) = \frac{1}{4} \left(\sin^2 2\theta + \sin^4 \theta \sin^2 2\varphi \right).$$

The Liouville integrals are supplemented by the two related Wojciechowski integrals $I_s^{(1)} = \hat{\mathcal{I}} I_s$ with leading-term coefficients linear in momenta: $g_s = \hat{\mathcal{I}} f_s$.

$$\begin{aligned} \{f_{\frac{3}{2}}, g_{\frac{3}{2}}\} &= 18(f_{\frac{3}{2}}^2 - f_2), & \{f_2, g_2\} &= 8(4f_2^2 - \frac{1}{3}f_{\frac{3}{2}}^2 - f_2), & \{f_{\frac{3}{2}}, f_2\} &= 0, \\ \{f_{\frac{3}{2}}, g_2\} &= \{f_2, g_{\frac{3}{2}}\} = 8f_{\frac{3}{2}}(3f_2 - 1), & \{g_{\frac{3}{2}}, g_2\} &= 4(2g_{\frac{3}{2}}f_2 - 3f_{\frac{3}{2}}g_2). \end{aligned}$$

Since the map $I_s \mapsto f_s$ is a Poisson algebra homomorphism, we immediately get the nontrivial brackets for the set of 5 integrals $H, I_s, I_s^{(1)}$:

$$\begin{aligned} \{I_{\frac{3}{2}}, I_{\frac{3}{2}}^{(1)}\} &= 18(I_{\frac{3}{2}}^2 - 2I_2H), & \{I_2, I_2^{(1)}\} &= 8(4I_2^2 - \frac{2}{3}I_{\frac{3}{2}}^2H - 4I_2H^2), \\ \{I_{\frac{3}{2}}, I_2^{(1)}\} &= \{I_2, I_{\frac{3}{2}}^{(1)}\} = 8I_{\frac{3}{2}}(3I_2 - 4H^2), & \{I_{\frac{3}{2}}^{(1)}, I_2^{(1)}\} &= 4(2I_{\frac{3}{2}}^{(1)}I_2 - 3I_{\frac{3}{2}}I_2^{(1)}). \end{aligned}$$

This is a particular realization of the quadratic algebra related to the Hamiltonian [Kuznetsov, 1995]

The integrals \mathcal{J}_s of spherical Hamiltonian \mathcal{I}

Using the leading angular coefficient f_2 , the "linear" integral of \mathcal{I} associated with l_2 is derived from its general form:

$$\mathcal{J}_2 = -\frac{1}{\sqrt{6}} \left(\frac{1}{256} \hat{\mathcal{I}}^4 + \frac{5}{16} \mathcal{I} \hat{\mathcal{I}}^2 + 4\mathcal{I}^2 \right) f_2.$$

Its explicit expression is complicated:

$$\begin{aligned} \mathcal{J}_2 = & \frac{1}{\sqrt{6}} \left[\frac{1}{16} (3 \cos 4\varphi - 11) p_\theta^4 - \frac{3}{4} \cot \theta \sin 4\varphi p_\theta^3 p_\varphi + \frac{3}{4} \cot^3 \theta \sin 4\varphi p_\theta p_\varphi^3 \right. \\ & \left. - \left(\frac{11+9 \cos 4\varphi}{8 \sin^2 \theta} + \frac{9}{4} \sin^2 2\varphi \right) p_\theta^2 p_\varphi^2 + \frac{3 \cos^4 \theta \cos 4\varphi + 21 \sin^4 \theta - 18 \sin^2 \theta - 11}{16 \sin^4 \theta} p_\varphi^4 \right] \\ & + g^2 K_1(\theta, \varphi) p_\theta^2 + g^2 K_2(\theta, \varphi) p_\theta p_\varphi + g^2 K_3(\theta, \varphi) p_\varphi^2 + g^4 K_4(\theta, \varphi), \end{aligned}$$

The system of equations (2) can be applied in order to express the coefficients $f_{\frac{3}{2},m}$ in terms of $f_{\frac{3}{2}}$:

$$f_{\frac{3}{2},-\frac{1}{2}} = \frac{1}{2\sqrt{3}} \hat{\mathcal{I}} f_{\frac{3}{2}}, \quad f_{\frac{3}{2},\frac{1}{2}} = \left(\frac{1}{8\sqrt{3}} \hat{\mathcal{I}}^2 + \frac{\sqrt{3}}{2} \mathcal{I} \right) f_{\frac{3}{2}}, \quad f_{\frac{3}{2},\frac{3}{2}} = \left(\frac{1}{48} \hat{\mathcal{I}}^2 + \frac{7}{12} \mathcal{I} \right) \hat{\mathcal{I}} f_{\frac{3}{2}}.$$

The integrals \mathcal{J}_s^m of spherical Hamiltonian \mathcal{I}

Then, using one obtains the spherical constants of motion associated with $I_{\frac{3}{2}}$, namely $\mathcal{J}_{\frac{3}{2}}^{\frac{3}{2}}$ and $\mathcal{J}_{\frac{3}{2}}^{\frac{1}{2}}$. Their explicit expressions are rather lengthy:

$$\begin{aligned} \mathcal{J}_{\frac{3}{2}}^{\frac{1}{2}} = & -\frac{3}{32} \sin^2 2\varphi p_\theta^6 - \frac{3}{16} \cot \theta \sin 4\varphi p_\theta^5 p_\varphi - \frac{3}{128} \frac{6 \cos^2 \theta + (13 - 3 \cos 2\theta) \cos 4\varphi}{\sin^2 \theta} p_\theta^4 p_\varphi^2 \\ & - \frac{3}{128} \frac{22 \sin^4 \theta - (43 - 53 \cos 2\theta) \cos 4\varphi \cos^2 \theta + 6 \cos 2\theta}{\sin^4 \theta} p_\theta^2 p_\varphi^4 \\ & - \frac{3}{128} \frac{\cos^2 \theta ((5 + 11 \cos 4\varphi) \sin^2 \theta + (2 - 9 \cos 2\theta \sin^2 \theta)(1 - \cos 4\varphi))}{\sin^6 \theta} p_\varphi^6 \\ & + \frac{3}{2} \cot \theta \sin 4\varphi p_\theta^3 p_\varphi^3 - \frac{3}{32} \frac{(7 - 9 \cos 2\theta) \cos^3 \theta \sin 4\varphi}{\sin^5 \theta} p_\theta p_\varphi^5 + \dots, \end{aligned}$$

$$\begin{aligned} \mathcal{J}_{\frac{3}{2}}^{\frac{3}{2}} = & -\frac{9}{32} \sin^2 2\varphi p_\theta^6 - \frac{9}{16} \cot \theta \sin 4\varphi p_\theta^5 p_\varphi - \frac{9}{64} \left(\frac{5 \cos 4\varphi + 3}{\sin^2 \theta} + 10 \sin^2 2\varphi \right) p_\theta^4 p_\varphi^2 \\ & - \frac{9}{64 \sin^4 \theta} (5 \cos^4 \theta \cos 4\varphi + 10 \sin^2 \theta - 5 \sin^4 \theta + 3) p_\theta^2 p_\varphi^4 + \frac{9}{16} \cot^5 \theta \sin 4\varphi p_\theta p_\varphi^5 \\ & + \frac{9 \cos^2 \theta}{64 \sin^6 \theta} (\cos^4 \theta \cos 4\varphi - 6 \sin^2 \theta - \sin^4 \theta - 1) p_\varphi^6 + \dots \end{aligned}$$

The algebraic relation among the four integrals of \mathcal{I}

- Clearly, \mathcal{I} , \mathcal{J}_2 , $\mathcal{J}_{\frac{3}{2}}^{\frac{1}{2}}$ and $\mathcal{J}_{\frac{3}{2}}^{\frac{3}{2}}$ cannot be functionally independent, since the spherical mechanics is 2 dimensional.
- Using Mathematica, one can verify the following algebraic relation,

$$\mathcal{J}_{\frac{3}{2}}^{\frac{3}{2}} = \frac{1}{3}\mathcal{J}_{\frac{3}{2}}^{\frac{1}{2}} + 2\sqrt{\frac{2}{3}}\mathcal{J}_2\mathcal{I} + \frac{1}{3}\mathcal{I}^3 + 4g^2\mathcal{I}^2.$$

- This is the only relation among the four constants of motion, since it can be verified also that $\mathcal{J}_{\frac{3}{2}}^{\frac{1}{2}}$ and $\mathcal{J}_{\frac{3}{2}}^{\frac{3}{2}}$ are not in involution with \mathcal{J}_2 . Even their free-particle parts ($g=0$ projects to the terms of highest order in the momenta) do not commute as is easy to verify.

Hence, \mathcal{J}_2 , $\mathcal{J}_{\frac{3}{2}}^{\frac{1}{2}}$ together with \mathcal{I} form the complete set of functionally independent constants of motion for the 2D spherical mechanics \mathcal{I} associated with 4-particle Calogero model with excluded center of mass. This confirms the superintegrability of that system.

Summary and discussion

A general approach to the constants of motion for conformal mechanics, based on $so(3)$ representation theory is proposed.

- Constants of motion for the spherical mechanics are constructed from a constant of motion for the initial conformal system.
- We have illustrated the effectiveness of our method on the example of the rational A_3 Calogero model and its spherical mechanics. For the latter we have constructed a complete set of functionally independent constants of motion, proving its intuitively obvious superintegrability.
- Unfortunately, our approach does not allow one to select a commuting subset of constants of motion for the spherical mechanics (if integrable), as well as to reveal the functionally independent constants of motions.
- Another task is to construct the complete set of integrals for the spherical mechanics associated with N -particle Calogero system.